

UNITED STATES DEPARTMENT OF COMMERCE United States Patent and Trademark Office Address: COMMISSIONER FOR PATENTS P.O. Box 1450 Alexandria, Virginia 22313-1450 www.uspto.gov

| APPLICATION NO.   | FILING DATE          | FIRST NAMED INVENTOR | ATTORNEY DOCKET NO. | CONFIRMATION NO. |
|---|----------------------|----------------------|---------------------|------------------|
| 10/796,167  | 03/10/2004           | Atsuhiko Takeuchi    | Q79698              | 3337             |
| 033.3   | 7590 02/14/2007      | EXAMINER             |                     |                  |
| SUGHRUE MION, PLLC<br>2100 PENNSYLVANIA AVENUE, N.W.<br>SUITE 800<br>WASHINGTON, DC 20037 |                      |                      | MARTIN, LAURA E     |                  |
|   |                      |                      | ART UNIT            | PAPER NUMBER     |
|   |                      |                      | 2853                |                  |
|   |                      |                      |                     |                  |
| SHORTENED STATUTOR  | Y PERIOD OF RESPONSE | MAIL DATE            | DELIVERY MODE       |                  |
| 3 MONTHS  |                      | 02/14/2007           | PAPER               |                  |

# Please find below and/or attached an Office communication concerning this application or proceeding.

If NO period for reply is specified above, the maximum statutory period will apply and will expire 6 MONTHS from the mailing date of this communication.

|  | Application No.  | Applicant(s)   |  |  |  |
|--|--|--|--|--|--|
|  | 10/796,167   | TAKEUCHI, ATSUHIKO   |  |  |  |
| Office Action Summary  | Examiner   | Art Unit   |  |  |  |
|  | Laura E. Martin  | 2853   |  |  |  |
| The MAILING DATE of this communication apperiod for Reply  | ppears on the cover sheet wit  | h the correspondence address   |  |  |  |
| A SHORTENED STATUTORY PERIOD FOR REP WHICHEVER IS LONGER, FROM THE MAILING I extensions of time may be available under the provisions of 37 CFR 1 after SIX (6) MONTHS from the mailing date of this communication.  If NO period for reply is specified above, the maximum statutory perior. Failure to reply within the set or extended period for reply will, by statu. Any reply received by the Office later than three months after the mail earned patent term adjustment. See 37 CFR 1.704(b).   | DATE OF THIS COMMUNIC<br>1.136(a). In no event, however, may a red<br>d will apply and will expire SIX (6) MON<br>the, cause the application to become ABA | CATION.  Poply be timely filed  THS from the mailing date of this communication.  ANDONED (35 U.S.C. § 133). |  |  |  |
| Status   |  |  |  |  |  |
| 1) Responsive to communication(s) filed on 18.  2a) This action is FINAL. 2b) Th  3) Since this application is in condition for allow closed in accordance with the practice under   | is action is non-final. rance except for formal matte  | • •  |  |  |  |
| Disposition of Claims  |  |  |  |  |  |
| 4) ⊠ Claim(s) 1 and 3-11 is/are pending in the approach 4a) Of the above claim(s) is/are withdrest 5) □ Claim(s) is/are allowed.  6) ⊠ Claim(s) 1 and 3-11 is/are rejected.  7) □ Claim(s) is/are objected to.  8) □ Claim(s) are subject to restriction and.  | rawn from consideration.   |  |  |  |  |
| Application Papers   |  |  |  |  |  |
| 9) The specification is objected to by the Examir 10) The drawing(s) filed on is/are: a) accepted any objection to the   | ccepted or b) objected to t  |  |  |  |  |
| Replacement drawing sheet(s) including the correct 11) The oath or declaration is objected to by the figure 11.  | ection is required if the drawing(   | s) is objected to. See 37 CFR 1.121(d).  |  |  |  |
| Priority under 35 U.S.C. § 119   |  |  |  |  |  |
| 12) Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f).  a) All b) Some color None of:  1. Certified copies of the priority documents have been received.  2. Certified copies of the priority documents have been received in Application No  3. Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)).  * See the attached detailed Office action for a list of the certified copies not received. |  |  |  |  |  |
| Attachment(s)  1) Notice of References Cited (PTO-892)  2) Notice of Draftsperson's Patent Drawing Review (PTO-948)  3) Information Disclosure Statement(s) (PTO/SB/08)  Paper No(s)/Mail Date   | Paper No(s   | ummary (PTO-413)<br>)/Mail Date<br>nformal Patent Application<br>  |  |  |  |

#### **DETAILED ACTION**

#### Claim Rejections - 35 USC § 103

The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:

(a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.

Claims 1, 3, and 5-9 are rejected under 35 U.S.C. 103(a) as being unpatentable over Arquilevich et al. (US 20020060709) in view of Endo (US 20020085057).

#### Arquilevich et al. discloses the following claim limitations:

As per claim 1, Arquilevich et al. teaches a recording position correction method for correcting position deviation in a sub-scanning direction crossing a main scanning direction of a recording position on a medium to be recorded [0019], wherein an inkjet type recording apparatus performs recording on said medium to be recorded by ejecting ink from a plurality of nozzles while allowing a recording head [0019], on which nozzle arrays comprising said plurality of nozzles provided in said sub-scanning direction are arranged in said main scanning direction, to perform scanning along at least one of forward and backward paths in said main scanning direction [0006], comprising: an ejection step of ejecting said ink from said plurality of nozzles onto said medium to be recorded [0006]; a measurement step of measuring an amount of position deviation in said sub-scanning direction of an ink dot recorded [0019]; and correcting the position deviation caused by a tilt of the recording head [0067]; a correction step of previously shifting and correcting a recording position of an ink dot to be recorded on said material for each of said plurality of nozzles based on said measured amount of said position

Application/Control Number: 10/796,167

Art Unit: 2853

deviation [0019], a recording position correction method, wherein ink is ejected from at least one nozzle of each of two nozzle arrays [0006], and the recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of deviation of an ink dot ejected and recorded form said nozzle of said nozzle arrays in said correction step [0019].

As per claim 3, Arquilevich et al. teaches a recording position correction method, wherein ink is further ejected from a nozzle [0006].

As per claim 5, Arquilevich et al. teaches a recording position correction method, wherein said ink is ejected while said recording head performs scanning along said forward and/or backward path(s) [0073] in said main scanning direction in said ejection step, and said recording position of said ink dot is previously shifted and corrected in said correction step [0019] based on an intermediate value between an amount of position deviation of an ink dot ejected and recorded in case said ink is ejected while said recording head performs scanning along said forward path in said main scanning direction [0018] and an amount of position deviation of an ink dot ejected and recorded in case said ink is ejected while said recording head performs scanning along said backward path [0073].

As per claim 6, Arquilevich et al. teaches a recording position correction method, wherein said ink is ejected while said recording head performs scanning along said forward and/or backward path(s) in said main scanning direction in said ejection step [0073], and correction is performed in said correction step, wherein said recording position of an ink dot to be recorded along said forward path in said main scanning direction is previously shifted based on an amount of position deviation in case said recording head performs scanning along said

forward path in said main scanning direction and said recording position of an ink dot to be recorded along said backward path in said main scanning direction is previously shifted based on an amount of position deviation in case said recording head performs scanning along said backward path in said main scanning direction [0019] and [0063].

As per claim 7, Arquilevich et al. teaches a recording position correction method wherein ink is ejected from at least one nozzle of each of two nozzle arrays [0006]. As per claim 8, Arquilevich et al. teaches an inkjet type recording apparatus for performing recording on said medium to be recorded by ejecting ink from a plurality of nozzles while allowing a recording head, on which nozzle arrays comprising said plurality of nozzles provided in said sub-scanning direction [0019] are arranged in said main scanning direction, to perform scanning along at least one of forward and backward paths in said main scanning direction [0006], comprising a correcting unit for previously shifting and correcting a recording position of an ink dot to be recorded on said material for each of said plurality of nozzles based on an amount of position deviation in a sub-scanning direction crossing said main scanning direction of an ink dot ejected and recorded from said plurality of nozzles [0019].

As per claim 9, Arquilevich et al. teaches a computer program [0008] for correcting position deviation of an ink dot ejected and recorded from a plurality of nozzles in a subscanning direction crossing a main scanning direction, wherein an inkjet type recording apparatus allows a recording head [0019], on which nozzle arrays comprising said plurality of nozzles provided in said sub-scanning direction are arranged in said main scanning direction [0006], to perform scanning along at least one of forward and backward paths in said main scanning direction [0073], comprising a correction function of previously shifting and correcting

Page 5

Art Unit: 2853

a recording position of an ink dot to be recorded on said material for each of said plurality of nozzles based on an amount of position deviation of an ink dot ejected and recorded from said plurality of nozzles in said sub-scanning direction crossing said main scanning direction [0019].

Arquilevich et al. does not disclose the following claim limitations:

As per claim 1, Arquilevich et al. does not teach ink ejected from at least one nozzle of each of two nozzle arrays most distanced from each other in the main scanning direction among a plurality of nozzle arrays in said ejection step.

As per claim 3, Arquilevich et al. does not teach ink further ejected from a nozzle of a nozzle array among said plurality of nozzle arrays except said two nozzle arrays in said ejection step, and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from at least one nozzle of each of said two nozzle arrays and at least one nozzle of said nozzle array except said two nozzle arrays in said correction step.

As per claim 7, Arquilevich et al. does not teach ink is ejected from at least one nozzle of each of two nozzle arrays which eject said ink of two colors respectively among said plurality of nozzle arrays as priority is given to a color of which density is highest in said ejection step, and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from said nozzle of said two nozzle arrays in said correction step.

As per claim 8, Arquilevich et al. does not teach a recording head on which nozzle arrays comprising the plurality of nozzles provided in a sub-scanning direction ar arranged in a main scanning direction, wherein the ink is ejected from at least one nozzle of each of two nozzle

arrays most distanced from each other in the main scanning direction among the plurality of nozzle arrays.

As per claim 9, Arquilevich et al. does not teach performing recording on a medium to be recorded by ejecting ink from at least one nozzle of each of two nozzle arrays most distanced from each other in the main scanning direction among a plurality of nozzle arrays, the nozzle of said two nozzle arrays are most distanced from each other in the main scanning direction.

### Endo et al. discloses the following claim limitations:

As per claim 1, Endo teaches ink ejected from at least one nozzle of each of two nozzle arrays most distanced from each other in said main scanning direction among said plurality of nozzle arrays in said ejection step [0087] (figure 11, there are three nozzle arrays (K<sub>D</sub> and C<sub>D</sub>; C<sub>L</sub> and M<sub>D</sub>; and M<sub>L</sub> and Y<sub>D</sub>), and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from said nozzle of said two nozzle arrays in said correction step [0084].

As per claim 3, Endo teaches said ink is further ejected from a nozzle of a nozzle array among said plurality of nozzle arrays except said two nozzle arrays in said ejection step [0104], and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from at least one nozzle of each of said two nozzle arrays and at least one nozzle of said nozzle array except said two nozzle arrays in said correction step [0084].

As per claim 7, Endo teaches ink ejected from at least one nozzle of each of two nozzle arrays which eject said ink of two colors respectively among said plurality of nozzle arrays as priority is given to a color of which density is highest in said ejection step (figure 11, elements 1 and 2), and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from said nozzle of said two nozzle arrays in said correction step [0084].

As per claim 8, Endo teaches a recording head on which nozzle arrays comprising the plurality of nozzles provided in a sub-scanning direction are arranged in a main scanning direction, wherein the ink is ejected from at least one nozzle of each of two nozzle arrays most distanced from each other in the main scanning direction among the plurality of nozzle arrays [0087] (figure 11, there are three nozzle arrays (K<sub>D</sub> and C<sub>D</sub>; C<sub>L</sub> and M<sub>D</sub>; and M<sub>L</sub> and Y<sub>D</sub>).

As per claim 9, Endo teaches performing recording on a medium to be recorded by ejecting ink from at least one nozzle of each of two nozzle arrays most distanced from each other in the main scanning direction among a plurality of nozzle arrays [0087] (figure 11, there are three nozzle arrays (K<sub>D</sub> and C<sub>D</sub>; C<sub>L</sub> and M<sub>D</sub>; and M<sub>L</sub> and Y<sub>D</sub>), the nozzle of said two nozzle arrays are most distanced from each other in the main scanning direction.

It would have been obvious to one of ordinary skill in the art at the time of the invention to modify the recording position correction method of Aquilevich et al. as modified with the disclosure of Endo in order to more effectively correct recording position errors.

Claim 4 is rejected under 35 U.S.C. 103(a) as being unpatentable over Arquilevich et al. (US 20020060709) and Endo (US 20020085057) in further view of Yuji (JP 05-330088).

As per claim 4, Arquilevich et al. teaches a recording position correction method, wherein the ink is ejected from a plurality of nozzles [0006] and said recording position of said ink dot is previously shifted and corrected for each of said colors in said correction step [0019].

As per claim 4, Aquilevich et al. does not teach ink ejected from said plurality of nozzles in order that a color of said ink from each of said nozzle arrays is different from one another in said ejection step, and said recording position of said ink dot is previously shifted and corrected for each of said colors in said correction step.

As per claim 4, Yuji teaches ink ejected from said plurality of nozzles in order that a color of said ink from each of said nozzle arrays is different from one another in said ejection step (figure 4, elements 1K, 1C, 1M, and 1Y; [0023-0030]).

It would have been obvious to one of ordinary skill in the art at the time of the invention to modify the recording position correction method of Arquilevich et al. with the disclosure of Yuji in order to more effectively correct recording position errors.

Claim 10 is rejected under 35 U.S.C. 103(a) as being unpatentable over Arquilevich et al. (US 20020060709) and Endo (US 20020085057, and further in view of Boleda et al. (US 6331038).

As per claim 10, Arquilevich et al. discloses the method of claim 1.

As per claim 10, Arquilevich et al. does not disclose a first step for measuring a distance between a ink dot ejected from a first nozzle array and an ink dot ejected from a second nozzle array; and a second step for determining a position deviation based on the measured distance.

As per claim 10, Boleda et al. discloses a first step for measuring a distance between a ink dot ejected from a first nozzle array and an ink dot ejected from a second nozzle array; and a second step for determining a position deviation based on the measured distance (column 5, lines 35-55).

It would have been obvious to one of ordinary skill in the art at the time of the invention to modify the recording position correction method of Arquilevich et al. with the disclosure of Boleda et al. in order to more effectively correct recording position errors.

Claim 11 is rejected under 35 U.S.C. 103(a) as being unpatentable over Arquilevich et al. (US 20020060709) and Endo (US 20020085057, and further in view of Bruch et al. (US 20020163551).

As per claim 11, Arquilevich et al. discloses the method of claim 1.

As per claim 11, Arquilevich et al. does not disclose a correction step correcting recording timings of each of the nozzles based on the position deviation, said recording timings defining a timing at which the nozzle ejects the ink.

As per claim 11, Bruch et al. discloses a correction step correcting recording timings of each of the nozzles based on the position deviation, said recording timings defining a timing at which the nozzle ejects the ink [0017; 0121-0122].

It would have been obvious to one of ordinary skill in the art at the time of the invention to modify the recording position correction method of Arquilevich et al. with the disclosure of Bruch et al. in order to more effectively correct recording position errors.

Claim 1 is rejected under 35 U.S.C. 103(a) as being unpatentable over Yeh et al. (US 20050151767) in view of Endo (US 20020085057).

## Yeh et al. discloses the following claim limitations:

As per claim 1, Yeh et al. teaches a recording position correction method for correcting position deviation in a sub-scanning direction crossing a main scanning direction of a recording position on a medium to be recorded, wherein an inkjet type recording apparatus performs recording on said medium to be recorded by ejecting ink from a plurality of nozzles while allowing a recording head, on which nozzle arrays comprising said plurality of nozzles provided in said sub-scanning direction are arranged in said main scanning direction, to perform scanning along at least one of forward and backward paths in said main scanning direction, comprising: an ejection step of ejecting said ink from said plurality of nozzles onto said medium to be recorded [0031]; a measurement step of measuring an amount of position deviation in said sub-scanning direction of an ink dot recorded [0014]; and correcting the position deviation caused by a tilt of the recording head [0105]; a correction step of previously shifting and correcting a recording position of an ink dot to be recorded on said material for each of said plurality of nozzles based on said measured amount of said position deviation [0015], a recording position correction method, wherein ink is ejected from at least one nozzle of each of two nozzle arrays [0006], and

the recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of deviation of an ink dot ejected and recorded form said nozzle of said nozzle arrays in said correction step [0014-0016].

As per claim 1, Yeh et al. does not teach ink ejected from at least one nozzle of each of two nozzle arrays most distanced from each other in the main scanning direction among a plurality of nozzle arrays in said ejection step.

As per claim 1, Endo teaches ink ejected from at least one nozzle of each of two nozzle arrays most distanced from each other in said main scanning direction among said plurality of nozzle arrays in said ejection step [0087] (figure 11, there are three nozzle arrays (K<sub>D</sub> and C<sub>D</sub>; C<sub>L</sub> and M<sub>D</sub>; and M<sub>L</sub> and Y<sub>D</sub>), and said recording position of said ink dot to be recorded on said material for each of said plurality of nozzles is previously shifted and corrected based on an amount of position deviation of an ink dot ejected and recorded from said nozzle of said two nozzle arrays in said correction step [0084].

It would have been obvious to one of ordinary skill in the art at the time of the invention to modify the recording position correction method of Yeh et al. as modified with the disclosure of Endo in order to more effectively correct recording position errors.

## Response to Arguments

The applicant argues that "the cited references fail to teach or suggest determining a position deviation caused by a tilt of the recording head and correcting the position deviation

Application/Control Number: 10/796,167 Page 12

Art Unit: 2853

caused by the recording head". The examiner would first like to note that Yeh et al. does teach the position deviation caused by tilt of the recording head. The examiner would also like to note that in Arquilevich et al. [0067], the reference teaches a test pattern (figure 7) to align the printhead in multiple ways, including about the z-axis (rotating or tilting).

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Laura E. Martin whose telephone number is (571) 272-2160. The examiner can normally be reached on Monday - Friday, 7:00 - 3:30.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Stephen D. Meier can be reached on (571) 272-2149. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

Laura E. Martin

MANISH S. SHAH PRIMARY EXAMINER

2/12/07